Routing Algorithms CS 571 Fall 2006

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Distributed Routing Algorithms

• Assumptions

- Network is modeled as a connected, undirected graph
- Nodes represent <u>both</u> destinations and relays (No distinction between routers and hosts)
- Each node has a unique ID (natural number)
- Edges are communication channels (bidirectional)
 - Edges may also have an associated "length" or "cost"
 - $d[i,j] = length of edge between i and j (<math>\infty$ if no edge exists)
 - Each node knows the lengths of its incident edges
 - Each node knows the identity of nodes it is connected to
- Nodes may not communicate except via channels

Problem Statement

- At convergence, for every node i and j:
 - $D_i[j]$ is the length of the shortest path from i to j
 - $h_i[j]$ is the next hop on the shortest path from i to j
- Algorithm converges if channels are not broken

Bellman-Ford Algorithm

 Based on R. Bellman's well-known principle of optimality, which in this context, says:

> If the <u>first step</u> on the shortest path from i to j is k then the rest is the shortest path from k to j (Suppose not, i.e. there is some shorter path from k to j. Then a shorter path from i to i to j exists, namely that first step followed by that path!.)



Distributed Bellman-Ford Algorithm

- Initialize: For each i and j: D_i[j] := d[i,j]
- At each i, iterate forever:

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\forall j: D_i[j] = min_k d[i,k] + D_k[j]
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or:
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for each j:
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for each neighbor k:

if $(d[i,k] + D_k[j] < D_i[j])$

{ $h_i[j] := k; D_i[j] := d[i,k] + D_k[j]$ }

- Nodes exchange their Di[j] tables periodically
 - Vector of distances \Rightarrow "Distance Vector" Algorithm





Distance-Vector Algorithms

- Advantage: Simple
- Disadvantage: Convergence time after topology/cost change depends on graph & costs!
 - May take a long time to detect changes & stabilize
 - Especially when the network becomes disconnected "Counting to Infinity" problem: Cost just keeps increasing Meanwhile, packets loop!
 - Partial solutions: "split horizon", "poison reverse" (see text)
- Disadvantage: Routing messages can be expensive
 - Dump entire forwarding table in each message!

Link-State Algorithms

- Basic Idea:
 - Nodes exchange topology information
 - Each announces the state of its attached links
 - Link-state announcements
 - Link-state announcements are broadcast throughout the network
 - Flooding mechanism implements a broadcast function
 - Each node builds a graph model of the network
 - Collects every other node's link-state announcements
 - Each node runs Dijkstra's all-nodes shortest-path algorithm on its graph
 - Requirement: <u>all nodes have the same graph model</u>!

Flooding Mechansim

- Every node forwards every new flooded message to all of its neighbors
 - "New" = not already in the node's database
- Challenge: distinguishing new from old
 - Solution: sequence numbers on LSAs
 - But: What about wrapping sequence numbers?
- Challenge: lost messages
 - Solution: acknowledge received flooded LSAs
 - Each node retransmits until ack received on each link

Simplified Link-State Example ...after B, C, & E flood their LSAs

Link-State Algorithms

- Advantages:
 - Nodes send information about only their attached links
 - Fast convergence after change
- Disadvantages:
 - Each node "knows" the whole topology!
 - Dijkstra running time grows with topology
 - Flooding consumes bandwidth