#### Devices and the Hardware/Software Interface CS 571 Fall 2006





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### What Network Hardware Does

#### • Transmit:

- Add framing information
- Serialize data from memory
- Gain access to channel via MAC Protocol (if applicable)
- <u>Modulate signal</u> to transmit symbols per physical protocol
- Implement Error Detection protocol (if applicable)
- Inform software (via interrupt) when transmission is complete
- Receive:
  - <u>Derive symbols</u> from physical signal
  - Recognize <u>station address</u> (if applicable)
  - <u>Strip framing, de-serialize</u> into memory
  - Perform <u>error-detection</u> checks (if applicable), signaling errors
  - Inform software (via interrupt) when frame is received

# Background: Threads of Control

- At any time, the CPU is executing instructions of at most one thread of control
  - Part of a: user program, OS, or device driver,
- When an interrupt occurs, CPU begins executing instructions of a special thread
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- When an interrupt occurs, CPU begins executing instructions of a special thread
  - Interrupt-handling routine of device driver
    - Code may be anywhere
    - Pointer to code ("<u>interrupt vector</u>") is stored in a low memory location associated with that device
  - Hardware automatically...
    - 1. Saves current state (on the interrupt stack)
    - 2. Begins loading instructions from that location
    - ...when that device raises an interrupt
- Devices may have different interrupts for receiving and transmitting

# What Software Does

- Inform hardware of buffer (memory) locations
  - Where incoming frames should be placed
  - Where frames to be transmitted are located
  - <u>Buffer descriptors</u>: pointers to memory areas for hardware use
  - For small frames (e.g. single characters), data is passed directly via <u>data registers</u>
- Inform hardware when buffers are ready to use
  - Receive buffers: empty
  - Transmit buffers: full, ready to send
  - Implemented by setting/clearing a bit in the buffer descriptor
- Add addressing information if applicable
  - E.g. Ethernet
- Deal with any errors signaled by device
  - E.g. framing errors, checksum errors

# How Do S/W & H/W Communicate?

- Through <u>device registers</u>
  - Special memory locations
  - Readable/writable by (privileged) software
- $H/W \rightarrow S/W$ : Registers indicate:
  - When a buffer is ready for s/w to service (by setting a bit)
    - Why isn't just interrupting sufficient?
  - When an error has occurred
  - Device status (ready, synchronizing, ...)
- $S/W \rightarrow H/W$ : Registers control:
  - Where buffers are
  - Device configuration
    - E.g. for async: # bits/frame, # stop bits
  - When a buffer is ready for h/w to service (by setting a bit)

#### Example Hardware Interface



#### Example Ethernet Config/Status Register



### Software Bit-Diddling

- Accessing registers:
  - Set a pointer (to the appropriate word size) to the (fixed!) address of the register
    - This only works in the kernel!
    - Can be troublesome if the device control register addresses are not fixed! (Pre-Plug-n-Play PC devices)
  - Read/write indirectly via the pointer

```
#define ETHER_MCSR 0xfff78420
unsigned int regValue, *csr;
csr = ETHER_MCSR;
regValue = *csr;
```

# Software Bit-Diddling

- Setting individual bits:
  - Get the current value
  - OR in the desired bit
  - E.g., to turn on Loopback mode (bit 3):
     #define LOOPBACK\_FLAG 0x8 // or (1<<3)
     \*csr |= LOOPBACK\_FLAG;</pre>
- Clearing individual bits:
  - Get the current value
  - AND with the complement of the desired bit
  - To turn off Loopback mode:

\*csr &= ~LOOPBACK\_FLAG;

# Software Bit-Diddling

- Complementing individual bits
  - XOR with the desired bit
     \*csr ^= LOOPBACK\_FLAG; // invert the flag!
- Reading groups of bits as a number:
  - AND the register value with the desired bits
  - Shift to proper magnitude
  - E.g., to check number of retries (bits 4-6):

```
#define RETRYCOUNT_SHIFT 4
#define RETRYCOUNT_MASK 0x70
numRetries = *csr & RETRYCOUNT_MASK;
numRetries >>= RETRYCOUNT_SHIFT;
```

Assumptions:

- User-space C program using TCP via "sockets" interface
- Sending a 500-byte message
- Machine connected to an Ethernet
- Modern Operating System
- No prior messages sent
- N.B. This is generic and greatly simplified!



- Application calls "send(sock#, bufPtr, 500)"
  - Run-time C library implementation of send() pushes arguments on stack
  - Implementation executes a "system call trap" instr.
  - Address of kernel trap svcing routine loaded into PC
  - Processor changes to privileged mode



- 2. Trap handler invokes kernel implementation of send() system call
  - Validates arguments (e.g., pointer is in the proc's address space)
  - Copies user data into kernel address space, adds buffer header
  - Locates the state data structure for the socket
  - Verify the socket state is OK to transmit
  - Appends the data to the socket's send queue (assumed empty)



- 3. System call invokes (indirectly) socket's sk\_send function
  - Invokes TCP "send\_data()" function, which:
    - Retrieves the relevant TCP state info
    - Checks whether it is possible to send anything (flow ctl)
    - Constructs 20-byte TCP header, prepends to message
  - TCP send\_data invokes "ip\_output()" with packet



- 4. ip\_output(...)
  - Gets destination IP address from TCP state data structure (layering violation)
  - Looks up that address in forwarding table to get a route (= logical interface + next hop IP address)
  - Prepends 20-byte IP header to TCP packet
  - Invokes the interface's output routine, bound to Eth\_output()



#### 4. Eth\_output(...)

- Resolves next-hop IP address to Ethernet address via ARP (may queue)
- Prepend 14-byte Ethernet header (incl. dest addr)
- If there is an available TxBufDescriptor, make it point to packet data
- If necessary, start the hardware device
- Free the kernel buffer hdr



- 5. Control returns up the stack
  - Success indication returned to application program
- 6. Hardware eventually transmits packet per Ethernet protocol



# Packet Transmission: Highlights

- Message <u>queued</u> in at least two places:
  - Socket transmit queue
    - May wait if socket is flow-controlled at transport level
  - (Maybe) ARP queue
    - Waiting for reply from target
  - Device output queue
    - May wait if channel is busy
- Packet processing happens in single thread of control all the way to device driver
- When send() returns, message may or may not have been transmitted

- 1. Hardware recognizes frame addressed to this station
  - Places packet into memory per next free RxBD
  - Hardware generates device interrupt



- 2. Current thread is interrupted; Ethernet interrupt service routine runs
  - Checks device status for errors
  - Verifies dest. address matches device address
  - Allocates kernel buffer hdr for packet data
  - Determines next protocol (IP)
  - Strips Ethernet header
  - Places buffer header in that protocol's input queue
  - Make RxBD point to a fresh buffer
  - Schedule the kernel <u>net service</u> <u>thread</u> to run
  - Return from interrupt; scheduler runs highest priority thread



- Net service thread detects nonempty queue, calls ip\_input(), which:
  - Dequeues packet
  - Sanity-checks IP header
  - Checks that packet's destination IP address = one of this device's addresses
  - Determines next-higher protocol
  - Invokes that protocol's input routine indirectly via "switch table" In this case, the actual routine is tcp\_input()



- 4. tcp\_input()
  - Retrieves relevant protocol state, using both IP and TCP headers
  - Determines if data is acceptable per TCP sliding window protocol
  - If so:
    - Strips IP + TCP headers by advancing buffer pointer
    - Retrieves associated socket state
    - Places packet payload in socket receive queue
    - If any application process is blocked on the queue, make it runnable
  - Returns
- 5. Net service thread blocks if no packet in net-level (IP) queue



- 6. Application calls "recv(sock#, buffer, 1000")
  - Run-time C library implementation of recv() pushes arguments on stack
  - Implementation executes a "system call trap" instr.
  - Address of kernel trap svcing routine loaded into PC
  - Processor changes to privileged mode
- Note: this step may happen <u>before</u> previous steps



- Trap handler invokes kernel implementation of recv() system call
  - Validates arguments (e.g., pointer is in the proc's address space)
  - Invokes socket's recv() function
  - Locates the state data structure for the socket
  - Verifies the socket state is OK to receive
  - If there is data in the socket queue
    - Copy it into the user's buffer; free kernel buffer header
    - Return
  - Else block until data arrives



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  - If there is data in the socket queue
    - Copy it into the user's buffer; free kernel buffer header and buffer
    - Return
  - Else block until data arrives



# Packet Reception Highlights

- Control flows from the bottom up
- Three different threads of control
  - Hardware interrupt
    - Must run very fast because it blocks everything else
  - High-priority "network service" thread
    - Processes data via function calls <u>upward</u> through stack
  - User program
- Data <u>must queue</u> somewhere between hardware and user program
  - There exists an "Asynchronous-synchronous" interface
- In this example, there are two queues
  - IP input
  - User input

(What happens when these queues get full?)

## Packet Reception Highlights

 Some protocol layers have to determine which next-higher layer to invoke by looking at their <u>own</u> header information

- Examples: Ethernet, IP

- Typically this is done <u>indirectly</u>, via a table of protocol functions
  - Header field value used as index into protocol table